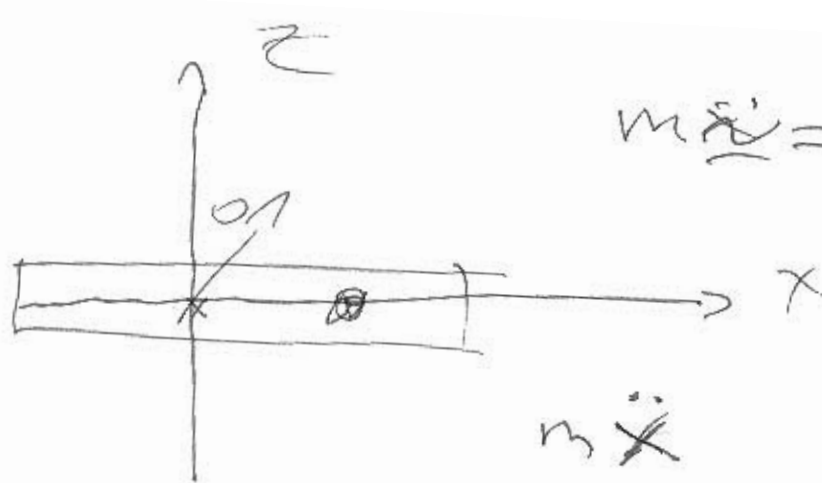




$$m\ddot{\underline{x}} = \underline{F} - 2m\underline{\omega} \times \underline{v} -$$

$$-m\underline{\omega} \times (\underline{\omega} \times \underline{r}) -$$

$$-m\underline{\dot{\omega}} \times \underline{r}$$

$$\underline{r}' = \underline{r}'(x(t), t)$$

$$\underline{\omega} = (\omega, 0, 0) \quad \underline{F} = \underline{N}$$

$$\ddot{\underline{r}} = (\ddot{x}, \ddot{y}, \ddot{z}) =$$

$$\ddot{\underline{r}} = (\ddot{x}, 0, 0)$$

$$\ddot{\underline{r}} = (\ddot{x}, \ddot{y}, 0)$$

$$\ddot{\underline{r}} = (x(t), 0, 0)$$

$$\begin{aligned} & \hat{e}_z \times \hat{e}_y \\ & -\hat{e}_y \times \hat{e}_z \end{aligned}$$

$$m\ddot{x} = 0 + m\omega^2 x$$

$$0 = m\ddot{y} = N_y - 2m\omega v$$

$$0 = m\ddot{z} = N_z$$

$$\ddot{x} = \omega^2 x \quad / e^{\lambda t}$$

$$x(t)$$

$$\lambda^2 = \omega^2$$

$$\lambda = \pm \omega$$

$$e^{\omega t} \quad e^{-\omega t}$$

$$x(0) = 0$$

$$\dot{x}(0) = v$$

$$x(t) = c_1 e^{\omega t} + c_2 e^{-\omega t}$$

$$0 = x(0) = c_1 + c_2 \quad \frac{A}{2} = c_1 = c_2$$

$$-\dot{x}(t) = c_1 \omega e^{\omega t} - c_2 \omega e^{-\omega t} =$$

$$v = \dot{x}(0) = c_1 \omega - c_2 \omega = \frac{A}{2} (\omega - (-1)\omega) =$$

$$v = A \omega$$

$$A = \frac{v}{\omega} \text{ s}$$

$$\dot{x}(t) = A \frac{1}{2} \underbrace{(e^{\omega t} - e^{-\omega t})}_{\text{sh}(\omega t)}$$

$$\ddot{x}(t) = -\frac{D}{m} x + \omega^2 x$$

$$\ddot{x}(t) = -\left(\frac{D}{m} - \omega^2\right) x$$

$$\frac{D}{m} - \omega^2 < 0 \Rightarrow \textcircled{1.}$$

$$\frac{D}{m} - \omega_0^2 = 0$$

$$\frac{D}{m} - \omega^2 > 0$$

ω_0

$$x(t) = A \cos(\omega_0 t + \varphi_0)$$

$$\dot{x}(t) = -A\omega \sin(\omega_0 t + \varphi_0)$$

$$\begin{cases} x(0) = A \cos(\varphi_0) \\ \dot{x}(0) = -A\omega \sin(\varphi_0) \end{cases}$$

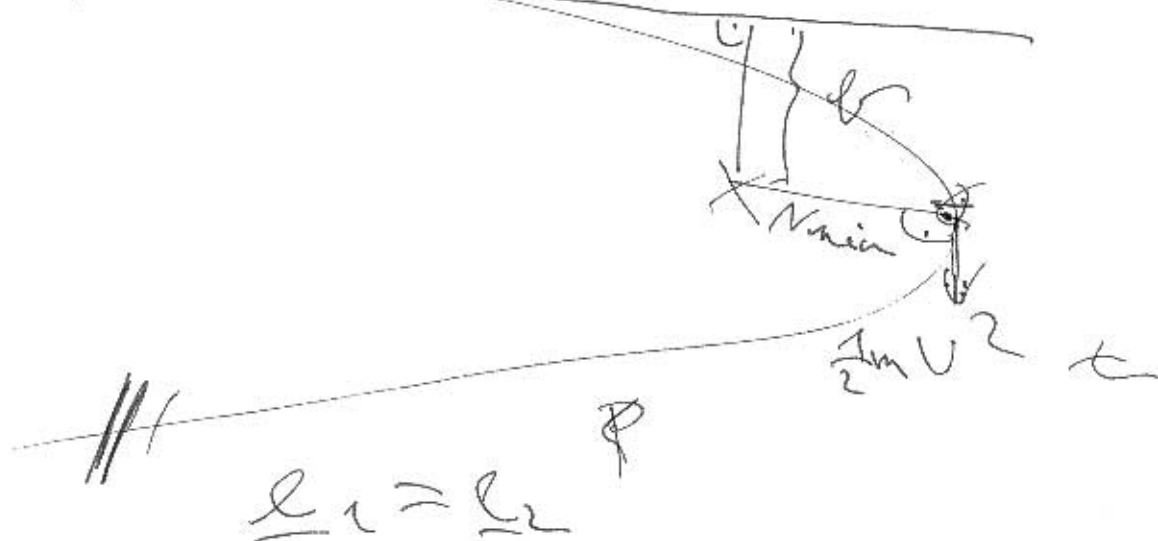
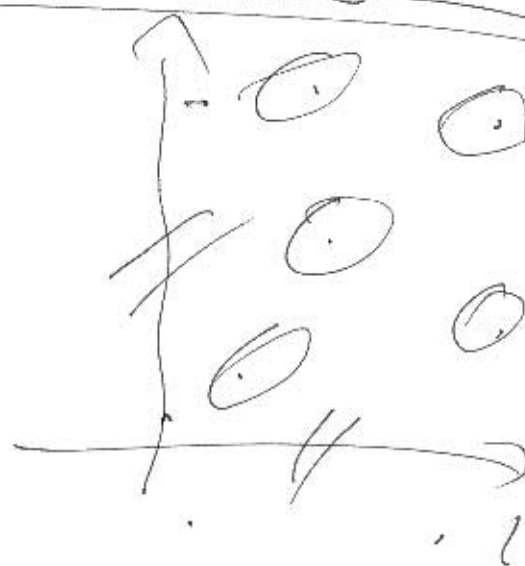
$$\frac{\dot{x}(0)}{x(0)} = -\omega \tan(\varphi_0)$$

$$\dot{x}(0) \leadsto$$

$$\begin{aligned} \textcircled{2} \quad x(t) &= R \cos(\omega t + \delta) \\ y(t) &= R \sin(\omega t + \delta) \end{aligned}$$

$$\begin{cases} \dot{x}(t) \\ \dot{y}(t) \end{cases}$$

$$\textcircled{3} \quad \text{H.P.}$$



$$\mathbb{R} \quad \boxed{E, l} \rightsquigarrow$$

$$r(\varphi) = \frac{p}{1 + \varepsilon \cos(\varphi - \varphi_0)}$$

$$\varphi_0 = 0$$

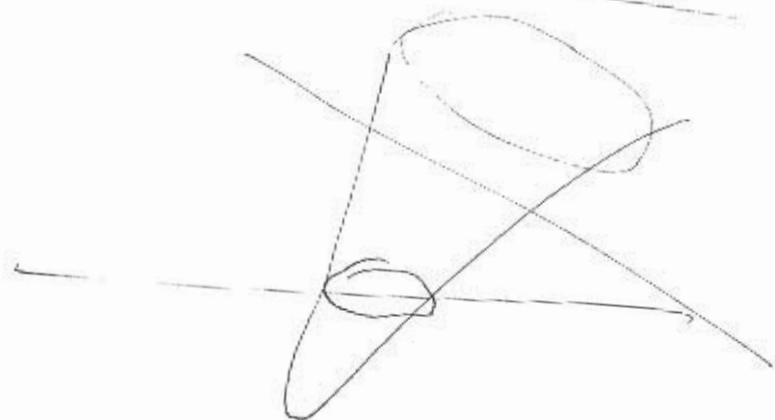
$$r_{\min} = \frac{p}{1 + \varepsilon}$$

E, l

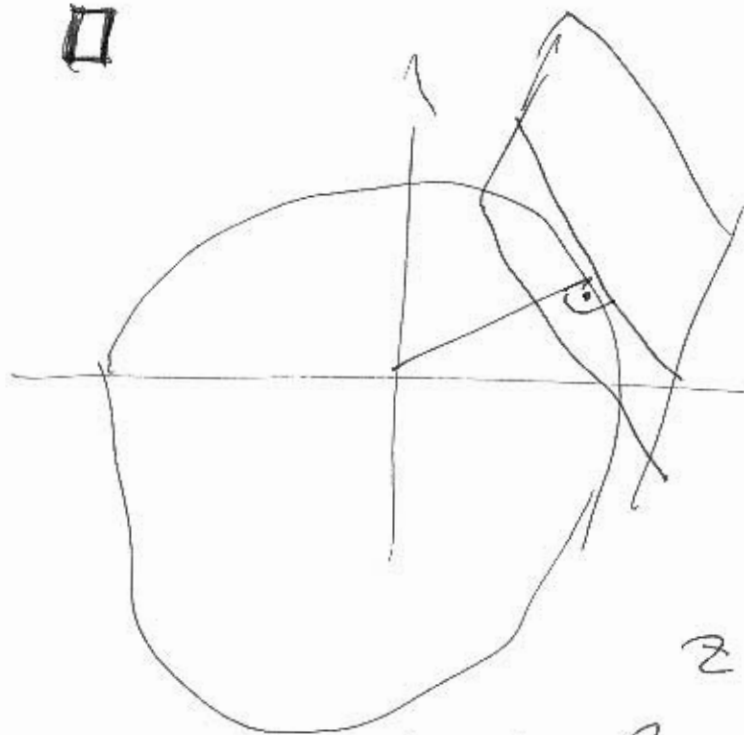
$$\varepsilon, p$$

$$p = \frac{e^2}{m A}$$

$$\varepsilon = \sqrt{1 + \frac{2E}{m} \frac{e^2}{A^2}}$$

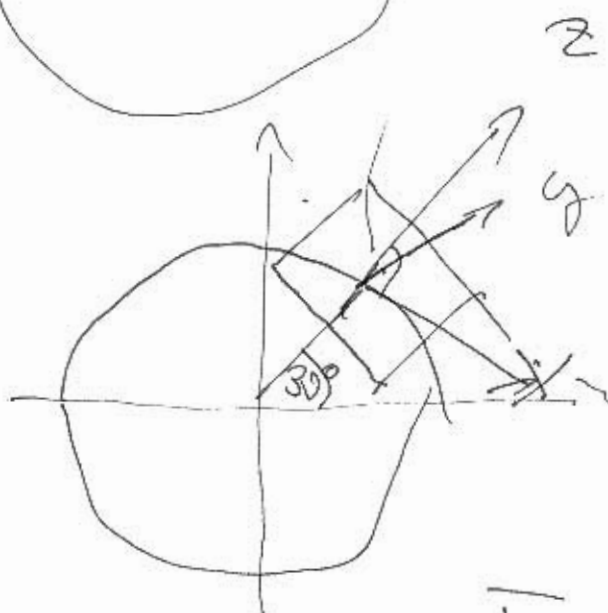


□



$$T = \frac{1}{2} I \omega^2$$

$$\omega =$$



Szerelvény

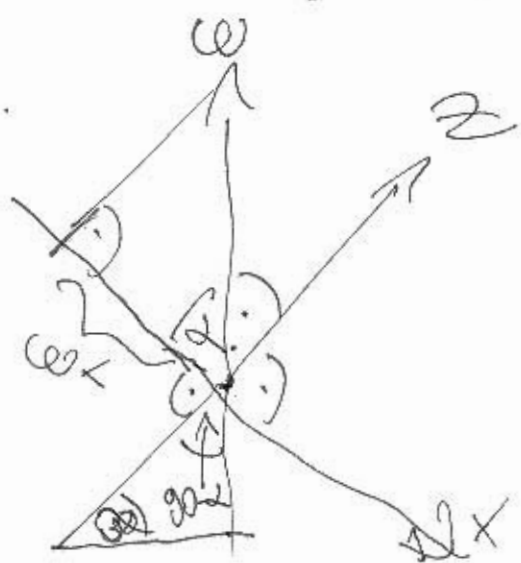
 mg mg

$$\underline{g} = (0, 0, -g)$$

$$m \ddot{\underline{r}} = \underline{F} - 2m(\underline{\omega} \times \underline{v}) + 0$$

$$\underline{F} = \underline{N} + m \underline{g}$$

m

 $\underline{\omega} \times \underline{v}$ 

$$\left\{ \begin{array}{l} \underline{v} = (0, v, 0) \\ \underline{x} = (0, y, 0) \\ \underline{a} = (0, 0, 0) \end{array} \right.$$

 $\alpha = 30$

$$\underline{\omega} = \omega (-\cos \alpha, \sin \alpha, 0)$$

$$\underline{\omega} = \omega \left(-\frac{\sqrt{3}}{2}, \frac{1}{2}, 0 \right)$$

$$\underline{\omega} \times \underline{v} = \underline{\omega} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} & 0 \\ 0 & v & 0 \end{vmatrix} =$$

$$= 0\hat{i} + \frac{\sqrt{3}}{2} v \hat{j} - \frac{\sqrt{3}}{2} v \omega \hat{k}$$

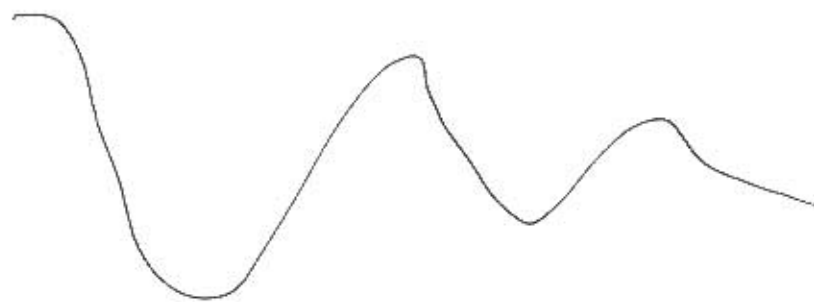
~~12~~

$$0 = m\ddot{x} = N_x \hat{i}$$

$$0 = m\ddot{y} = N_y \hat{j}$$

$$0 = m\ddot{z} = -mg + N_z + 2 \cdot \frac{\sqrt{3}}{2} v \omega \hat{k}$$

$$N_z = mg + 2 \cdot \frac{\sqrt{3}}{2} v \omega$$



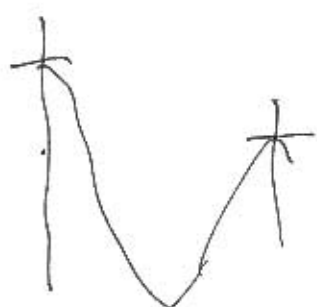
$$\beta = \frac{\gamma}{2m}$$

$$m\ddot{x} = -\frac{\gamma}{m}\dot{x} - Dx$$

$$\ddot{x} + 2\beta\dot{x} + \frac{D}{m}x = 0$$

$$x(t) = e^{-\beta t} \cos(\omega t + \phi_0)$$

$$\omega = \sqrt{\omega_0^2 - \beta^2}$$



$$T = \frac{2\pi}{\omega}$$

$$\omega_0 = \sqrt{\frac{D}{m}}$$

$$x(t+T) \neq x(t)$$

$$\frac{x(t+T)}{x(t)} = \frac{e^{-\beta(t+T)}}{e^{-\beta t}} = e^{-\beta T}$$

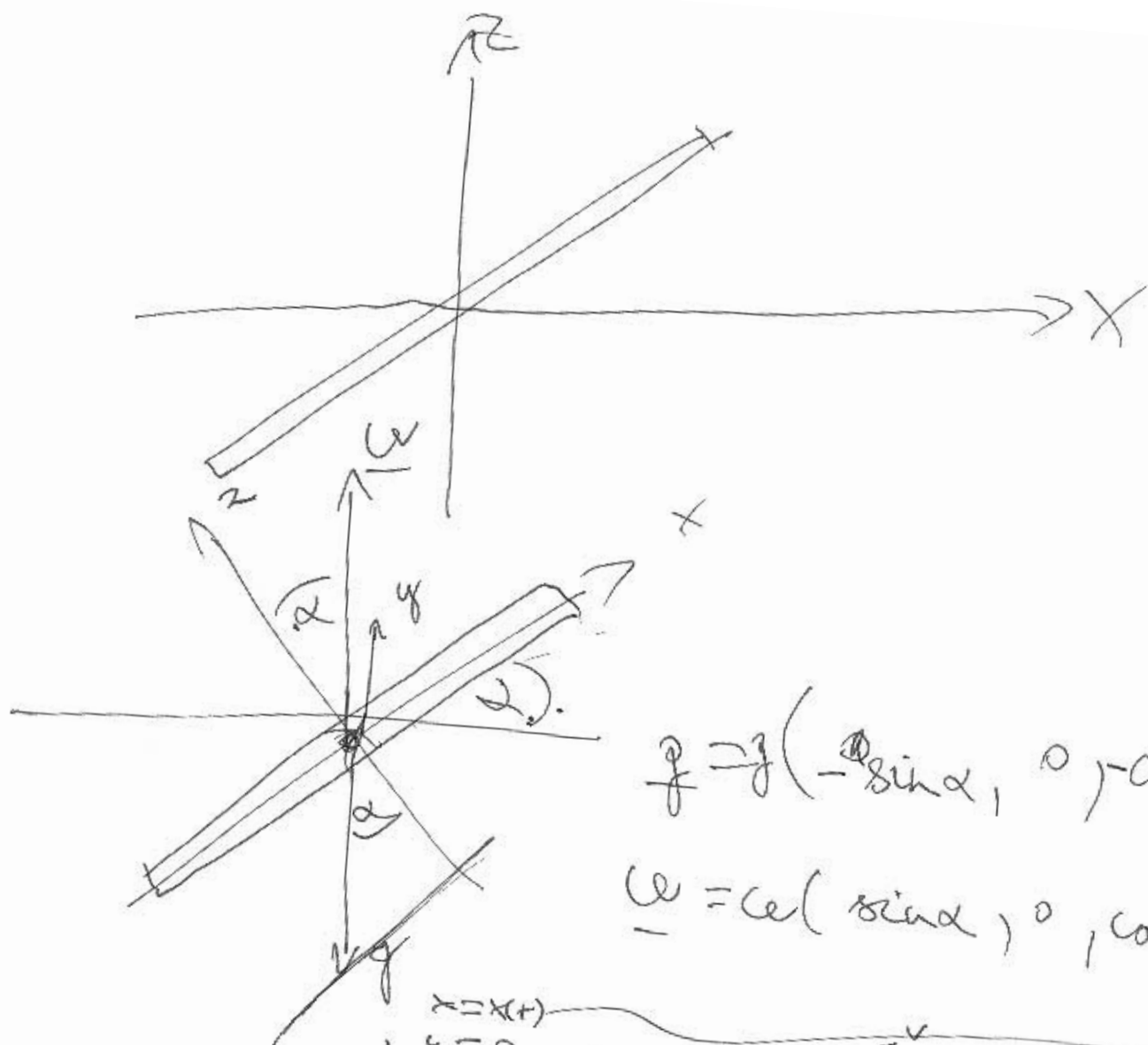
$$\frac{x(t)}{x(t+T)} = e^{\beta T}$$

$$\frac{x(t+T)}{x(t)} = e^{-\beta T}$$

$$A = \ln(x(t)/x(t+T)) = \beta T$$

$$\frac{10}{1}$$

$$\omega = \sqrt{\omega_0^2 - \beta^2}$$



$$\hat{r} = \hat{r}(-\sin \alpha, 0, \cos \alpha)$$

$$\underline{\omega} = \omega(\sin \alpha, 0, \cos \alpha)$$

$$x = x(t)$$

$$y = 0$$

$$z = 0$$

$$\ddot{x} = \ddot{x}(t)$$

$$\dot{x} = \dot{x}(t)$$

$$\ddot{y} = 0$$

$$\dot{y} = 0$$

$$\ddot{z} = 0$$

$$\dot{z} = 0$$

$$\underline{\omega} \times \underline{r}$$

$$\omega \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \sin \alpha & 0 & \cos \alpha \\ 0 & 0 & 0 \end{vmatrix}$$

$$= 0 + \omega \cos \alpha \hat{j} + 0$$

$$\underline{\omega} \times \underline{r}$$

$$=$$

$$\omega \cos \alpha \hat{j}$$

$$\underline{\omega} \times (\underline{\omega} \times \underline{r}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \sin \alpha & 0 & \cos \alpha \\ 0 & \omega \cos \alpha & 0 \end{vmatrix}$$

$$\omega^2$$

$$= (-\hat{n} \cos^2 \alpha + \hat{j} \sin \alpha \cos \alpha) \omega^2 x \neq$$

$$m \underline{\ddot{v}} = \underline{F} - \cancel{mg} 2m \underline{\omega} \times \underline{v} - \cancel{m \underline{\omega} \times (\underline{\omega} \times \underline{r})}$$

$$m \underline{\ddot{v}} = m \underline{g} - 2m(\underline{\omega} \times \underline{v}) - m \underline{\omega} \times (\underline{\omega} \times \underline{r})$$

$$m \ddot{x} = mg \sin \alpha - 2 \cdot 0 + m \cos^2 \alpha \omega^2 x$$

$$0 = m \ddot{y} = 0 + N_y - 2m \omega v \cos \alpha \neq 0$$

$$0 = m \ddot{z} = N_z \neq mg \cos \alpha + 0 \neq \omega^2 m \cos \alpha \sin \alpha$$

$$\underline{\ddot{x}} = -g \sin \alpha + \cos^2 \alpha \omega^2 x$$

$$\ddot{x} = -\lambda \dot{x} + mg$$

$$0 = -\lambda \dot{x} - mg$$

$$x(t) = \underline{\omega + \omega^2}$$